

**IN THE CLAIMS**

Please amend the claims as follows.

1. (Cancelled).

2. (Currently Amended) The system as claimed in Claim [[1]] 4, wherein said single carrier signal is a vestigial sideband signal.

3. (Currently Amended) The system as claimed in Claim [[1]] 4, wherein said synchronization circuit is capable of obtaining [[a]] the coarse frequency estimate of said single carrier signal by locating a pilot carrier signal on an average power spectrum of said single carrier signal.

4. (Currently Amended) A system for providing frequency domain

synchronization for a single carrier signal, comprising: ~~The system as claimed in Claim 1~~  
a synchronization circuit that is capable of receiving the single carrier signal, obtaining a  
coarse frequency estimate of the single carrier signal, and obtaining a fine frequency estimate of the  
single carrier signal;

wherein said synchronization circuit is capable of obtaining [[a]] the fine frequency estimate of said single carrier signal using [[the]] a frequency error  $\Delta f_p$  where  $\Delta f_p$  is given by the equation:

$$\Delta f_p = [ 1 / (2\pi N T_s) ] [ \text{Arg} [ X_{pr,q}(0) / X_{pr,q+1}(0) ] ]$$

where  $[ 1 / (N T_s) ]$  is [[the]] a frequency spacing, and where  $T_s$  is [[the]] a sampling period, and where  $X_{pr}(0)$  is the transmitted signal with constant frequency error in [[the]] a zeroth bin, and where  $\text{Arg} [ X_{pr,q}(0) / X_{pr,q+1}(0) ]$  is [[the]] a phase of a pilot carrier signal in the zeroth bin.

5. (Currently Amended) A system for providing frequency domain synchronization for a single carrier signal, comprising: ~~The system as claimed in Claim 1~~  
a synchronization circuit that is capable of receiving the single carrier signal obtaining a coarse frequency estimate of the single carrier signal, and obtaining a fine frequency estimate of the single carrier signal;

wherein said synchronization circuit ~~further~~ comprises a three state machine for obtaining a final frequency estimate of said single carrier signal, said three state machine capable of obtaining a first frequency estimate, ~~and capable of~~ obtaining a second frequency estimate with a known fixed frequency estimate of a positive one fourth bin spacing, and ~~capable of~~ obtaining a third frequency estimate with a known fixed frequency estimate of a negative one fourth bin spacing.

6. (Original) The system as claimed in Claim 5 wherein said three state machine is capable of determining which two of the three frequency estimates are closest in value, and capable of obtaining an average of the two closest frequency estimates, and capable of calculating said final frequency estimate of said single carrier signal by adding one fourth of a bin spacing to said average of the two closest frequency estimates.

7. (Currently Amended) The system as claimed in Claim 5 where said three state machine is capable of obtaining said first, second, and third frequency estimates of [[a]] the single carrier signal by obtaining a coarse frequency estimate of said single carrier signal by locating a pilot carrier signal on an average power spectrum of said single carrier signal, and by obtaining a fine frequency estimate of said single carrier signal using [[the]] a frequency error  $\Delta f_p$  where  $\Delta f_p$  is given by the equation:

$$\Delta f_p = [ 1 / (2\pi N T_s) ] [ \text{Arg} [ X_{pr,q}(0) / X_{pr,q+1}(0) ] ]$$

where  $[ 1 / (N T_s) ]$  is [[the]] a frequency spacing, and where  $T_s$  is [[the]] a sampling period, and where  $X_{pr}(0)$  is the transmitted signal with constant frequency error in [[the]] a zeroth bin, and where  $\text{Arg} [ X_{pr,q}(0) / X_{pr,q+1}(0) ]$  is [[the]] a phase of a pilot carrier signal in the zeroth bin.

8. (Original) The system as claimed in Claim 7 wherein said synchronization circuit has a linear transfer function.

9. (Original) A system for providing frequency domain synchronization for a single carrier signal, said system comprising:

a synchronization circuit comprising a Fast Fourier Transformer, a coarse frequency estimate circuit coupled to an output of said Fast Fourier Transformer, and a fine frequency estimate and

phase estimate circuit coupled to an output of said Fast Fourier Transformer, and

a DC estimator circuit capable of being coupled to said fine frequency estimate and phase estimate circuit in place of said output of said Fast Fourier Transformer, said DC estimator circuit capable of providing a time domain DC estimate to said fine frequency estimate and phase estimate circuit.

10. (Original) The system as claimed in Claim 9 wherein said DC estimator circuit calculates said time domain DC estimate,  $DC_{NEW}$ , from the equation:

$$DC_{NEW} = FFT(0) - Input(N) + Input(0)$$

where  $FFT(0)$  is a processed DC estimate, and where  $Input(N)$  is an input sample received  $N$  time periods earlier, and where  $Input(0)$  is a current input sample.

11. (Original) The system as claimed in Claim 10 wherein said DC estimator circuit receives the value of Input (N) from an output of a circular input buffer for said Fast Fourier Transformer, and wherein said DC estimator circuit receives the value of Input (0) from an output of a sample rate converter, and wherein said DC estimator circuit receives the value of FFT(0) from an output of an adder that adds the outputs of said coarse frequency estimate circuit and said fine frequency estimate and phase estimate circuit.

12. (Cancelled).

13. (Currently Amended) The method as claimed in Claim [[12]] 15, wherein said single carrier signal is a vestigial sideband signal.

14. (Currently Amended) The method as claimed in Claim [[12]] 15, wherein said step of obtaining [[a]] the coarse frequency estimate of said single carrier signal ~~in said synchronization circuit~~ comprises the step of:

locating a pilot carrier signal on an average power spectrum of said single carrier signal.

15. (Currently Amended) A method for providing frequency domain

synchronization for a single carrier signal, comprising the steps of: ~~The method as claimed in Claim~~

12

receiving a single carrier signal;

obtaining a coarse frequency estimate of the single carrier signal; and

obtaining a fine frequency estimate of the single carrier signal;

wherein said step of obtaining [[a]] ~~the~~ fine frequency estimate of said single carrier signal in  
said synchronization circuit comprises the step of [[:]] calculating said fine frequency estimate using  
[[the]] a frequency error  $\Delta f_p$  where  $\Delta f_p$  is given by the equation:

$$\Delta f_p = [ 1 / (2\pi N T_s) ] [ \text{Arg} [ X_{pr,q}(0) / X_{pr,q+1}(0) ] ]$$

where  $[ 1 / (N T_s) ]$  is [[the]] a frequency spacing, and where  $T_s$  is [[the]] a sampling period, and  
where  $X_{pr}(0)$  is the transmitted signal with constant frequency error in [[the]] a zeroth bin, and where  
 $\text{Arg} [ X_{pr,q}(0) / X_{pr,q+1}(0) ]$  is [[the]] a phase of a pilot carrier signal in the zeroth bin.

16. (Currently Amended) A method for providing frequency domain synchronization for a single carrier signal, comprising the steps of: ~~The method as claimed in Claim 12 further comprising the steps of:~~

receiving a single carrier signal;

obtaining a coarse frequency estimate of the single carrier signal;

obtaining a fine frequency estimate of the single carrier signal;

obtaining in a three state machine a first frequency estimate of said single carrier signal;

obtaining in said three state machine a second frequency estimate of said single carrier signal with a known fixed frequency estimate of a positive one fourth bin spacing; and

obtaining in said three state machine a third frequency estimate of said single carrier signal with a known fixed frequency estimate of a negative one fourth bin spacing.

17. (Original) The method as claimed in Claim 16 further comprising the steps of:

determining which two of said three frequency estimates are closest in value;

obtaining an average of the two closest frequency estimates; and

calculating a final frequency estimate of said single carrier signal by adding one fourth of a bin spacing to said average of the two closest frequency estimates.

18. (Currently Amended) The method as claimed in Claim 16 further comprising the step [[s]] of [[:]] obtaining said first, second and third frequency estimates of [[a]] the single carrier signal by:

obtaining a coarse frequency estimate of said single carrier signal by locating a pilot carrier signal on an average power spectrum of said single carrier signal; and by

obtaining a fine frequency estimate of said single carrier signal ~~obtaining a fine frequency estimate of said single carrier signal~~ using [[the]] a frequency error  $\Delta f_p$  where  $\Delta f_p$  is given by the equation:

$$\Delta f_p = [ 1 / (2\pi N T_s) ] [ \text{Arg} [ X_{pr,q}(0) / X_{pr,q+1}(0) ] ]$$

where  $[ 1 / (N T_s) ]$  is [[the]] a frequency spacing, and where  $T_s$  is [[the]] a sampling period, and where  $X_{pr}(0)$  is the transmitted signal with constant frequency error in [[the]] a zeroth bin, and where  $\text{Arg} [ X_{pr,q}(0) / X_{pr,q+1}(0) ]$  is [[the]] a phase of a pilot carrier signal in the zeroth bin.

19. (Currently Amended) The method as claimed in Claim 18 wherein said a synchronization circuit capable of obtaining the coarse and fine frequency estimates has a linear transfer function.

20. (Cancelled).

21. (Currently Amended) A method for providing frequency domain synchronization for a single carrier signal, comprising the steps of: ~~The method as claimed in Claim 20~~  
generating a time domain DC estimate in a DC estimator circuit; and  
providing said time domain DC estimate to a fine frequency estimate and phase estimate circuit;  
wherein said time domain DC estimate is provided to said fine frequency estimate and phase estimate circuit by switching an input of said fine frequency estimate and phase estimate circuit from an output of a Fast Fourier Transformer to an output of said DC estimator circuit.

22. (Currently Amended)

A method for providing frequency domain synchronization for a single carrier signal, comprising the steps of: ~~The method as claimed in Claim 20~~

generating a time domain DC estimate in a DC estimator circuit; and

providing said time domain DC estimate to a fine frequency estimate and phase estimate circuit;

wherein the step of generating said time domain DC estimate in said DC estimator circuit comprises the step of [[:]] calculating said time domain DC estimate, DC<sub>NEW</sub>, from the equation:

$$DC_{NEW} = FFT(0) - Input(N) + Input(0)$$

where FFT(0) is a processed DC estimate, and where Input(N) is an input sample received N time periods earlier, and where Input(0) is a current input sample.

23. (Currently Amended)

The method as claimed in Claim 22 further comprising

the steps of:

providing the value of Input(N) to said DC estimator circuit from an output of a circular input buffer for a Fast Fourier Transformer;

providing the value of Input(0) to said DC estimator circuit from an output of a sample rate converter; and

providing the value of FFT(0) from an output of an adder that adds the outputs of a coarse frequency estimate circuit and said fine frequency estimate and phase estimate circuit.